# Lecture 7: Matrix Equations and Matrix Inverses

#### Summary of Matrix Multiplication

Let A be an  $m \times n$  matrix with rows  $\mathbf{r}_1, \ldots, \mathbf{r}_m$  and B be an  $s \times p$  matrix with columns  $\mathbf{c}_1, \ldots, \mathbf{c}_p$ . Then:

(i) We can form the product  $A \cdot B$  if and only if n = s.

That is, we can only form the product  $A \cdot B$  if the number of columns in A equals the number of rows in B.

(ii) When 
$$r = s$$
, the  $(i, j)$ -entry of  $A \cdot B$  is  $\mathbf{r}_i \cdot \mathbf{c}_j$ .

(iii) If the product matrix  $A \cdot B$  exists, it is an  $m \times p$  matrix.

**Further Comments:** Assume  $A \cdot B$  exists, i.e., B is an  $m \times p$  matrix.

- (a) The columns of  $A \cdot B$  are  $A \cdot \mathbf{c}_1, A \cdot \mathbf{c}_2, \dots, A \cdot \mathbf{c}_p$ .
- (b) The rows of  $A \cdot B$  are  $\mathbf{r}_1 \cdot B, \mathbf{r}_2 \cdot B, \dots, \mathbf{r}_m \cdot B$ .
- (c) The product  $B \cdot A$  will not exist unless p = n.
- (d) Even if  $A \cdot B$  and  $B \cdot A$  are defined,  $A \cdot B$  need not equal  $B \cdot A$ .

### Properties of matrix multiplication:

Let A and B be  $m \times n$  matrices, C an  $n \times p$  matrix, D a  $p \times t$  matrix, E an  $s \times m$  matrix, and  $\alpha \in \mathbb{R}$ . Then: (i)  $(A \cdot C) \cdot D = A \cdot (C \cdot D)$ (ii)  $(A \cdot C)^t = C^t \cdot A^t$ 

(iii) 
$$(A+B) \cdot C = A \cdot C + B \cdot C$$

(iv) 
$$E \cdot (A+B) = E \cdot A + E \cdot B$$

(v) 
$$\alpha \cdot (A \cdot C) = (\alpha \cdot A) \cdot C = A \cdot (\alpha \cdot C)$$

Converting from a system of equations to a matrix equation

Start with a system of m linear equations in n unknowns:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$
  

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$
  

$$\vdots \qquad = \vdots$$
  

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m.$$

Let A denote the coefficient matrix and set  $x = \begin{vmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{vmatrix}$  and  $b = \begin{vmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{vmatrix}$ .

The we may rewrite the system of equations as a single matrix equation:

$$A \cdot x = b.$$

#### For example, if the system is

$$ax + by + cz = u$$
  
 $dx + ey + fz = v$ ,

then for 
$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$$
,  $x = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$  and  $u = \begin{bmatrix} u \\ v \end{bmatrix}$ , we get the matrix equation:

$$A \cdot x = u.$$

**Comment:** When we have a single numerical equation ax = b, i.e., one equation in one unknown, with  $a \neq 0$ , we can solve it by dividing both sides of the equation by a:  $x = \frac{b}{a}$ .

Equivalently: We multiply both sides of the equation by the multiplicative inverse of a, to get  $x = a^{-1} \cdot b$ . In some cases we can do this for a matrix equation.

In (extreme) detail: If we start with the simple equation ax = b, and multiply by  $a^{-1}$ , the sequence of steps we really have is:

$$ax = b$$
$$a^{-1} \cdot (ax) = a^{-1} \cdot b$$
$$(a^{-1} \cdot a)x = a^{-1} \cdot b$$
$$1 \cdot x = a^{-1} \cdot b$$
$$x = a^{-1} \cdot b$$

In some cases, we can perform the same process for a matrix equation.

#### Definition

Let A be an  $n \times n$  matrix and write  $I_n$  for the  $n \times n$  matrix with 1s down its main diagonal and zeroes elsewhere. I.e.,  $I_n = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$ . (i) We call  $I_n$  the name is the integration.

$$B \cdot I_n = B$$
 and  $I_n \cdot C = C$ ,

for all  $s \times n$  matrices B and  $n \times p$  matrices C. (ii) An  $n \times n$  matrix  $A^{-1}$  is called an *inverse matrix for A* if

$$A \cdot A^{-1} = I_n = A^{-1} \cdot A.$$

Consider 
$$A = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$$
. Then :  
 $A \cdot I_2 = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 3 \cdot 1 + 5 \cdot 0 & 3 \cdot 0 + 5 \cdot 1 \\ 1 \cdot 1 + 2 \cdot 0 & 1 \cdot 0 + 2 \cdot 1 \end{bmatrix} = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$ .

And:

$$I_{2} \cdot A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 \cdot 3 + 0 \cdot 1 & 1 \cdot 5 + 0 \cdot 2 \\ 0 \cdot 3 + 1 \cdot 1 & 0 \cdot 5 + 1 \cdot 2 \end{bmatrix} = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}.$$
  
Moreover: If we take  $A^{-1} = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}$ , then:  
 $A \cdot A^{-1} = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} \cdot \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} = A \cdot A^{-1}.$ 

## Example continued

We can use  $A^{-1}$  to solve the matrix equation:

$$\begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix}.$$

Multiplying this equation by  $A^{-1}$  we get

$$\begin{bmatrix} 2 & -5\\ -1 & 3 \end{bmatrix} \cdot \begin{pmatrix} 3 & 5\\ 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} x\\ y \end{bmatrix} = \begin{bmatrix} 2 & -5\\ -1 & 3 \end{bmatrix} \cdot \begin{bmatrix} 4\\ 6 \end{bmatrix}$$
$$\begin{pmatrix} \begin{bmatrix} 2 & -5\\ -1 & 3 \end{bmatrix} \cdot \begin{bmatrix} 3 & 5\\ 1 & 2 \end{bmatrix}) \cdot \begin{bmatrix} x\\ y \end{bmatrix} = \begin{bmatrix} 2 & -5\\ -1 & 3 \end{bmatrix} \cdot \begin{bmatrix} 4\\ 6 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0\\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x\\ y \end{bmatrix} = \begin{bmatrix} -22\\ 8 \end{bmatrix}$$
$$\begin{bmatrix} x\\ y \end{bmatrix} = \begin{bmatrix} -22\\ 8 \end{bmatrix}.$$

#### Example continued

Putting this all together, we can use an inverse matrix to solve the system of equations:

$$3x + 5y = 4$$
$$x + 2y = 6.$$

Solution: The system corresponds to the matrix equation  $A \cdot x = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$ , with  $A = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$ . From above, multiplying by  $A^{-1}$  yields  $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -22 \\ 8 \end{bmatrix}$ .

In other words, the solution to the system is

$$x = -22$$
 and  $y = 8$ .

## Class Example

(i) Verify that 
$$A^{-1} = \begin{bmatrix} -4 & -7 \\ -1 & -2 \end{bmatrix}$$
 is the inverse of the coefficient matrix  $A$  of the system:

$$-2x + 7y = -3$$
$$x - 4y = 6.$$

(ii) Convert the system of equations to a matrix equation and use  $A^{-1}$  to first solve the matrix equation, and then find a solution to the system.

Solution: (i) 
$$A \cdot A^{-1} = \begin{bmatrix} -2 & 7 \\ 1 & -4 \end{bmatrix} \cdot \begin{bmatrix} -4 & -7 \\ -1 & -2 \end{bmatrix} = \begin{bmatrix} -2 \cdot (-4) + 7 \cdot (-1) & -2 \cdot (-7) + 7 \cdot (-2) \\ 1 \cdot (-4) + (-4) \cdot -1 & 1 \cdot (-7) + (-4) \cdot (-2) \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

On the other hand,  $A^{-1} \cdot A =$ 

$$\begin{bmatrix} -4 & -7 \\ -1 & -2 \end{bmatrix} \cdot \begin{bmatrix} -2 & 7 \\ 1 & -4 \end{bmatrix} = \begin{bmatrix} -4 \cdot (-2) + (-7) \cdot 1 & -4 \cdot 7 + (-7) \cdot (-4) \\ -1 \cdot (-2) + (-2) \cdot 1 & -1 \cdot 7 + (-2) \cdot (-4) \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

(ii): The matrix equation is: 
$$A \cdot x = \begin{bmatrix} -3 \\ 6 \end{bmatrix}$$
, where  $A = \begin{bmatrix} -2 & 7 \\ 1 & -4 \end{bmatrix}$  and  $x = \begin{bmatrix} x \\ y \end{bmatrix}$ .

Multiplying by  $A^{-1}$  we get

$$\mathbf{x} = \mathbf{I}_2 \cdot \mathbf{x} = \mathbf{A}^{-1} \cdot \mathbf{A} \cdot \mathbf{x} = \mathbf{A}^{-1} \begin{bmatrix} -3\\ 6 \end{bmatrix} = \begin{bmatrix} -4 & -7\\ -1 & -2 \end{bmatrix} \cdot \begin{bmatrix} -3\\ 6 \end{bmatrix} = \begin{bmatrix} -30\\ -9 \end{bmatrix}.$$

Thus,

$$\begin{bmatrix} -30\\ -9 \end{bmatrix} = \mathsf{x} = \begin{bmatrix} x\\ y \end{bmatrix}$$

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Therefore, x = -30 and y = -9.

#### Properties of inverse matrices:

- (i) Only a square matrix can have an inverse, i.e., A must be an n × n matrix, for some n ≥ 1.
- (ii) Not every square matrix has an inverse.
- (iii) If A has an inverse, then the inverse is unique. That is, any invertible matrix has just one inverse.
- (iv) If A has an inverse, then so does  $A^{-1}$ , in which case  $(A^{-1})^{-1} = A$ .
- (v) If A and B are  $n \times n$  matrices with inverses  $A^{-1}$ ,  $B^{-1}$ , then  $A \cdot B$  has an inverse, and  $(A \cdot B)^{-1} = B^{-1} \cdot A^{-1}$ .
- (vi) If A is invertible, then  $A^t$  is invertible and  $(A^t)^{-1} = (A^{-1})^t$ .

#### Invertibility Criterion

The following theorem tells us when a matrix is invertible, and how to find its inverse.

**Theorem.** Let A be an  $n \times n$  matrix.

- (i) A has an inverse if and only if the rank of A equals n.
- (ii) If A has an inverse, then the following steps lead to  $A^{-1}$ :
  - (a) Form the  $n \times (2n)$  augmented matrix  $[A \mid I_n]$ .
  - (b) Perform elementary row operations until this augmented matrix has the form  $[I_n \mid B]$ .
  - (c) The matrix *B* emerging on the right portion of the augmented matrix is, in fact,  $A^{-1}$ .

**Very Important Point:** The rank of *A* equals the number of leading ones in the RREF of *A*.

Therefore, if A is an  $n \times n$  matrix, it has rank n if and only if it can be row reduced to  $I_n$ .

Thus, if A has rank n, the left-hand side of the augmented matrix  $[A \mid I_n]$  can be row reduced to  $I_n$ .

Show that the matrix  $A = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$  is invertible and find its inverse.

Solution: Start with the augmented matrix:  $\begin{bmatrix} 3 & 5 & | & 1 & 0 \\ 1 & 2 & | & 0 & 1 \end{bmatrix}$ , and try to transform the left hand side into  $I_2$ .

$$\begin{bmatrix} 3 & 5 & | & 1 & 0 \\ 1 & 2 & | & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 2 & | & 0 & 1 \\ 3 & 5 & | & 1 & 0 \end{bmatrix} \xrightarrow{-3 \cdot R_1 + R_2} \begin{bmatrix} 1 & 2 & | & 0 & 1 \\ 0 & -1 & | & 1 & -3 \end{bmatrix}$$
$$\xrightarrow{-1 \cdot R_2} \begin{bmatrix} 1 & 2 & | & 0 & 1 \\ 0 & 1 & | & -1 & 3 \end{bmatrix} \xrightarrow{-2 \cdot R_2 + R_1} \begin{bmatrix} 1 & 0 & | & 2 & -5 \\ 0 & 1 & | & -1 & 3 \end{bmatrix}.$$
us, *A* is invertible (it has rank 2) and its inverse is  $A^{-1} = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}$ ,

Th as before.

Determine if the matrix 
$$B = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 4 \\ 5 & 6 & 0 \end{bmatrix}$$
 is invertible. If so, find  $B^{-1}$ .  
Solution:  $\begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 5 & 6 & 0 & | & 0 & 1 \end{bmatrix} \xrightarrow{-5 \cdot R_1 + R_3} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 0 & -4 & -15 & | & -5 & 0 & 1 \end{bmatrix}$   
 $\xrightarrow{4 \cdot R_2 + R_3} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & -5 & 4 & 1 \end{bmatrix} \xrightarrow{-2R_2 + R_1} \begin{bmatrix} 1 & 0 & -5 & | & 1 & -2 & 0 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & -5 & 4 & 1 \end{bmatrix} \xrightarrow{-2R_2 + R_1} \begin{bmatrix} 1 & 0 & -5 & | & 1 & -2 & 0 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & -5 & 4 & 1 \end{bmatrix}$   
 $\xrightarrow{5 \cdot R_3 + R_1} \begin{bmatrix} 1 & 0 & 0 & | & -24 & 18 & 5 \\ 0 & 1 & 4 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & -5 & 4 & 1 \end{bmatrix} \xrightarrow{-4 \cdot R_3 + R_2} \begin{bmatrix} 1 & 0 & 0 & | & -24 & 18 & 5 \\ 0 & 1 & 0 & | & 20 & -15 & -4 \\ 0 & 0 & 1 & | & -5 & 4 & 1 \end{bmatrix}$   
Thus:  $B^{-1} = \begin{bmatrix} -24 & 18 & 5 \\ 20 & -15 & -4 \\ -5 & 4 & 1 \end{bmatrix}$ .

Check:

and

$$\begin{bmatrix} -24 & 18 & 5\\ 20 & -15 & -4\\ -5 & 4 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & 3\\ 0 & 1 & 4\\ 5 & 6 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 2 & 3\\ 0 & 1 & 4\\ 5 & 6 & 0 \end{bmatrix} \cdot \begin{bmatrix} -24 & 18 & 5\\ 20 & -15 & -4\\ -5 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & 1 \end{bmatrix}$$

Lecture 7: Matrix Equations and Matrix Inverses

#### Class Example

Find the inverses of the following matrices:  $A = \begin{bmatrix} 4 & -1 \\ 5 & -1 \end{bmatrix}$ ,  $B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & -3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ ,  $C = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$ , with a, b, c all non-zero.

Solution:

Т

$$\begin{bmatrix} 4 & -1 & | & 1 & 0 \\ 5 & -1 & | & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 5 & -1 & | & 0 & 1 \\ 4 & -1 & | & 1 & 0 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & | & -1 & 1 \\ 4 & -1 & | & 1 & 0 \end{bmatrix}$$
$$\xrightarrow{-4 \cdot R_1 + R_2} \begin{bmatrix} 1 & 0 & | & -1 & 1 \\ 0 & -1 & | & 5 & -4 \end{bmatrix} \xrightarrow{-1 \cdot R_2} \begin{bmatrix} 1 & 0 & | & -1 & 1 \\ 0 & 1 & | & -5 & 4 \end{bmatrix}.$$
Thus,  $A^{-1} = \begin{bmatrix} -1 & 1 \\ -5 & 4 \end{bmatrix}.$ 

$$\begin{bmatrix} 3 & -4 & 0 & | & 1 & 0 & 0 \\ 2 & -3 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & -1 & 0 & | & 1 & -1 & 0 \\ 2 & -3 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$
$$\xrightarrow{-2 \cdot R_1 + R_2} \begin{bmatrix} 1 & -1 & 0 & | & 1 & -1 & 0 \\ 0 & -1 & 0 & | & -2 & 3 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1 \cdot R_2} \begin{bmatrix} 1 & -1 & 0 & | & 1 & -1 & 0 \\ 0 & 1 & 0 & | & 2 & -3 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$
$$\xrightarrow{R_2 + R_1} \begin{bmatrix} 1 & 0 & 0 & | & 3 & -4 & 0 \\ 0 & 1 & 0 & | & 2 & -3 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} .$$
Thus,  $B^{-1} = \begin{bmatrix} 3 & -4 & 0 \\ 2 & -3 & 0 \\ 0 & 0 & 1 \end{bmatrix} = B!$ 

## Class Example continued

$$\begin{bmatrix} a & 0 & 0 & | & 1 & 0 & 0 \\ 0 & b & 0 & | & 0 & 1 & 0 \\ 0 & 0 & c & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\frac{1}{a} \cdot R_1}_{\frac{1}{b} \cdot R_2} \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{a} & 0 & 0 \\ 0 & 1 & 0 & | & 0 & \frac{1}{b} & 0 \\ 0 & 0 & c & | & 0 & 0 & 1 \end{bmatrix}$$
$$\xrightarrow{\frac{1}{c} \cdot R_3}_{\frac{1}{c} \cdot R_3} \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{a} & 0 & 0 \\ 0 & 1 & 0 & | & \frac{1}{b} & 0 \\ 0 & 0 & 1 & | & 0 & 0 & \frac{1}{c} \end{bmatrix}$$
Thus,  $C^{-1} = \begin{bmatrix} \frac{1}{a} & 0 & 0 \\ 0 & \frac{1}{b} & 0 \\ 0 & 0 & \frac{1}{c} \end{bmatrix}$ .